

# EFFECTIVE DYNAMICS FOR OPEN SYSTEM: TIME AVERAGE APPROACH

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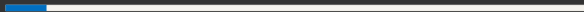
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# APPROACHES TO EFFECTIVE DYNAMICS



- Different time scales of dynamics
  - rapidly vs. slowly evolving components with large difference in time scales
  - Fast variables follow adiabatically slow degrees of freedom. (e.g. spinning top: While it is spinning at a high frequency, the rotation axis is usually precessing much slower. )
- Simpler (and more intuitive) description
  - smaller dimension of Hilbert space ( e.g. (3-level)  $\Lambda$  system  $\rightarrow$  effective 2-level system )
  - often possible to derive simple laws for slow variables when the scales are well separated
  - might be useful for gaining insight into gating operation or state engineering
- Less computational burden

# Formalisms for Effective Dynamics

- Adiabatic elimination (AE)
  - Standard technique Gardiner & Zoller (2000)
  - Sometimes tedious step of calculation in store
- Effective operator formalism Reiter & Sørensen (2012)
  - Easy-to-use AE for open systems
  - Only ground state manifold is maintained.
- Flow equation (FE) approach Kehrein (2006)
  - Analogous to renormalization group procedure
  - Not yet developed for open systems
- Time average (TA) formalism Gamel & James (2010)
  - Easy-to-use generalization of RWA
  - Analogous to FE in sense of not eliminating excited states
  - Developed for open systems in this work

# Comparison of Formalisms

## ○ In view of Hilbert space transformation

Kehrein (2006)

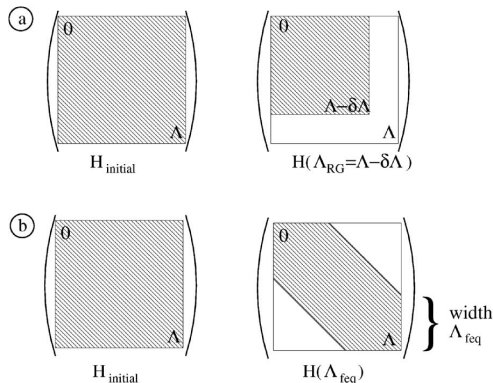


Fig. 1.1. Schematic view of different scaling approaches: (a) Conventional scaling methods successively reduce the high-energy cutoff  $\Lambda_{\text{RG}}$ . (b) Flow equations make the Hamiltonian successively more band-diagonal with an effective band width  $\Lambda_{\text{feq}}$

## ○ Classification

(a)  $\rightarrow$  Remove high energy sector (Renormalization group (RG), adiabatic elimination)

(b)  $\rightarrow$  Narrow energy band (Flow equation (FE), time average)

(RG, FE  $\rightarrow$  successive transformation)

# TIME AVERAGE FORMALISM FOR CLOSED SYSTEMS

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- Time average of an operator

$$\overline{O}(t) \equiv \int_{-\infty}^{\infty} dt' f(t-t') O(t') \quad [\text{or } \overline{O}(\omega) = f(\omega) O(\omega)]$$

- Gamal's time average:  $f(\omega) \sim \Theta(\omega_c - |\omega|)$

$$\overline{e^{\pm i\omega_n t}} = 0, \quad \overline{e^{\pm i(\omega_m + \omega_n)t}} = 0, \quad \overline{e^{\pm i(\omega_m - \omega_n)t}} = e^{\pm i(\omega_m - \omega_n)t}$$

(set  $\omega_c$  s.t.  $|\omega_m - \omega_n| < \omega_c < \omega_n$  for any  $\omega_m, \omega_n$ )

- Rotating wave approximation (RWA)

$\implies$  Time average with sharp cutting-off

$$\begin{aligned} H_{\text{Rabi}} &\sim (a e^{-i\omega t} + a^\dagger e^{i\omega t})(\sigma_- e^{-i\omega_0 t} + \sigma_+ e^{i\omega_0 t}) \\ &= a \sigma_+ e^{-i(\omega - \omega_0)t} + a^\dagger \sigma_- e^{i(\omega - \omega_0)t} + a \sigma_- e^{-i(\omega + \omega_0)t} + a^\dagger \sigma_+ e^{i(\omega + \omega_0)t} \end{aligned}$$

$$\therefore \overline{H_{\text{Rabi}}} \sim a \sigma_+ e^{-i(\omega - \omega_0)t} + a^\dagger \sigma_- e^{i(\omega - \omega_0)t} \quad (\longrightarrow H_{\text{JC}})$$



## Time Average Formalism (Cont'd)

- Other time average method:  $f(\omega) \sim \exp(-\omega^2/\omega_c^2)$   
 $\implies$  smooth frequency filtering [Wang & Haw (2015)]  
 $\implies$  The counter-rotating terms can survive but the dynamics is now dependent on  $\omega_c$ .
- von Neumann equation and its solution

$$d\rho/dt = -i[\lambda H(t), \rho] \implies \rho(t) = U(t) \rho(0) U^\dagger(t)$$

( $\lambda$ : a (real) bookkeeping parameter (later becomes unity))

- (Unitary) Time evolution operator

$$\begin{aligned} U(t) &\equiv \mathbf{T} e^{-i \int_0^t H(t') dt'} \quad (\mathbf{T}: \text{time-ordering operator}) \\ &= I - i\lambda \int_0^t dt_1 H(t_1) + (-i\lambda)^2 \int_0^t dt_1 \int_0^{t_1} dt_2 H(t_1) H(t_2) + \dots \\ &\equiv I + \lambda U_1(t) + \lambda^2 U_2(t) + \dots \end{aligned}$$

# Time Average Formalism (Cont'd)

- Inverse of the time evolution operator

$$\begin{aligned}U^{-1}(t) &= U^\dagger(t) = \tilde{\mathbf{T}} e^{+i \int_0^t H(t') dt'} \quad (\tilde{\mathbf{T}}: \text{anti-time-ordering operator}) \\ &= I + i\lambda \int_0^t dt_1 H(t_1) + (i\lambda)^2 \int_0^t dt_1 \int_0^{t_1} dt_2 H(t_2) H(t_1) + \dots \\ &= I + \lambda U_1^\dagger(t) + \lambda^2 U_2^\dagger(t) + \dots\end{aligned}$$

- Useful properties

$$U_1^\dagger = -U_1, \quad U_2^\dagger = U_1^2 - U_2, \quad i\dot{U}_n(t) = H(t)U_{n-1}(t), \dots$$

- Time-averaged evolution operator

$$\begin{aligned}\overline{\rho(t)} &= \overline{U(t) \rho_0 U^\dagger(t)} = \sum_{k=0}^{\infty} \lambda^k \sum_{j=0}^k \overline{U_{k-j} \rho_0 U_j^\dagger} \\ &\equiv \sum_{k=0}^{\infty} \lambda^k \mathcal{E}_k[\rho_0] \equiv \mathcal{E}[\rho_0] \quad (\rho_0 = \rho(0), \mathcal{E}_0 = I)\end{aligned}$$

# Time Average Formalism (Cont'd)

- Inverse of time-averaged evolution operator

$$\rho_0 = \mathcal{E}^{-1}[\bar{\rho}] \equiv \mathcal{F}[\bar{\rho}] \equiv \sum_k \lambda^k \mathcal{F}_k[\bar{\rho}]$$

- Identity relation:  $\mathcal{F}[\mathcal{E}[\rho]] = \sum_{k=0}^{\infty} \lambda^k \sum_{j=0}^k \mathcal{F}_j[\mathcal{E}_{k-j}[\rho]] = \rho$

$$\implies \mathcal{F}_0 = \mathcal{E}_0 = I, \quad \mathcal{F}_1 = -\mathcal{E}_1, \quad \mathcal{F}_2 = \mathcal{E}_1^2 - \mathcal{E}_2, \quad \dots$$

- Time average of von Neumann eq.

$$\begin{aligned} i\dot{\bar{\rho}}(t) &= i\dot{\mathcal{E}}[\rho_0] = i\dot{\mathcal{E}}[\mathcal{F}[\bar{\rho}(t)]] = i \sum_{k=0}^{\infty} \lambda^k \sum_{j=0}^k \dot{\mathcal{E}}_j[\mathcal{F}_{k-j}[\bar{\rho}(t)]] \\ &\equiv \sum_{k=0}^{\infty} \lambda^k \mathcal{L}_k[\bar{\rho}(t)], \end{aligned}$$

## Time Average Formalism (Cont'd)

- Time average of von Neumann eq. (Cont'd)

$$\mathcal{L}_0[\bar{\rho}] = i\dot{\mathcal{E}}_0[\mathcal{F}_0[\bar{\rho}]] = 0,$$

$$\mathcal{L}_1[\bar{\rho}] = i\dot{\mathcal{E}}_0[\mathcal{F}_1[\bar{\rho}]] + i\dot{\mathcal{E}}_1[\mathcal{F}_0[\bar{\rho}]] = [\bar{H}, \bar{\rho}],$$

$$\mathcal{L}_2[\bar{\rho}] = \overline{HU_1}\bar{\rho} + \overline{H\bar{\rho}U_1^\dagger} - \bar{\rho}\overline{U_1^\dagger H} - \overline{U_1\bar{\rho}H},$$

...

$$\text{where } \overline{AB} \equiv \overline{AB} - \bar{A}\bar{B}, \quad \overline{A\bar{\rho}B} \equiv \overline{A\bar{\rho}B} - \bar{A}\bar{\rho}\bar{B}.$$

- Master equation up to 2nd order

$$i\dot{\rho} = [H_{\text{eff}}, \rho] + \left\{ \frac{1}{2}(A - A^\dagger), \rho \right\} + \overline{H\bar{\rho}U_1^\dagger} - \overline{U_1\bar{\rho}H},$$

$$\left[ A \equiv \overline{HU_1}, \quad A^\dagger \equiv \overline{U_1^\dagger H}, \text{ and } H_{\text{eff}} \equiv \bar{H} + \frac{1}{2}(A + A^\dagger) \right]$$

# Time Average Formalism (Cont'd)

- Typical form of (interaction) Hamiltonian

$$H = H_0 + \sum_n h_n e^{i\omega_n t} + h_n^\dagger e^{-i\omega_n t} \quad (H_0 : \text{time-independent})$$

- Time-averaged master equation  $\implies$  Lindblad form!

$$\begin{aligned} i\dot{\bar{\rho}} &= [H_0, \bar{\rho}] + \sum_{m,n} \left[ \frac{l_m l_n^\dagger}{\omega_n} - \frac{l_n^\dagger l_m}{\omega_m}, \bar{\rho} \right] + \frac{2}{\omega_{mn}^-} (l_m \bar{\rho} l_n^\dagger + l_n^\dagger \bar{\rho} l_m) \\ &\implies [H_{\text{eff}}, \bar{\rho}] + \sum_{m,n} \frac{2}{\omega_{mn}^-} \left[ \mathcal{D}_{l_m, l_n^\dagger} \bar{\rho} - \mathcal{D}_{l_n^\dagger, l_m} \bar{\rho} \right] \end{aligned}$$

where  $\mathcal{D}_{A,B}\rho \equiv A\rho B - \frac{1}{2}(AB\rho + \rho AB)$ ,  $\frac{1}{\omega_{mn}^\pm} \equiv \frac{1}{2} \left( \frac{1}{\omega_m} \pm \frac{1}{\omega_n} \right)$ ,  
 $l_n \equiv h_n e^{i\omega_n t}$ , and

$$H_{\text{eff}} \equiv H_0 + \sum_{m,n} \frac{1}{\omega_{mn}^+} [l_m, l_n^\dagger].$$

# TIME AVERAGE FORMALISM FOR OPEN SYSTEMS

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# Time Average Formalism for an Open System

- Lindblad form of master equation in an open system

$$\frac{d\rho}{dt} = -i[H, \rho] + \sum_i (\mathcal{J}_{L_i} \rho - \mathcal{K}_{L_i} \rho),$$

where  $\mathcal{J}_L \rho \equiv L \rho L^\dagger$ ,  $\mathcal{K}_L \rho \equiv \frac{1}{2} (L^\dagger L \rho + \rho L^\dagger L)$

- Let  $\mathcal{K}_{\text{tot}} = \sum_i \mathcal{K}_{L_i}$  then

$$\begin{aligned} e^{\mathcal{K}_{\text{tot}} t} \rho &= \left[ 1 + \mathcal{K}_{\text{tot}} t + \frac{1}{2} (\mathcal{K}_{\text{tot}} t)^2 + \dots \right] \rho \\ &= \rho + (K \rho + \rho K) t + \frac{1}{2} (K^2 \rho + 2K \rho K + \rho K^2) t^2 + \dots \\ &= e^{K t} \rho e^{K t} \quad \left( K \equiv \frac{1}{2} \sum_i L_i^\dagger L_i \right) \end{aligned}$$

$$\implies e^{K t} \dot{\rho} e^{K t} = -i \left( H_K \rho_K - \rho_K H_K^\dagger \right) + \sum_i \mathcal{J}_{L_{i,K}} \rho - e^{K t} (K \rho + \rho K) e^{K t}$$

with  $\rho_K \equiv e^{K t} \rho e^{K t}$ ,  $H_K \equiv e^{K t} H e^{-K t}$ ,  $L_{i,K} \equiv e^{K t} L_i e^{-K t}$ .

# Time Average Formalism for an Open System (Cont'd)

- Transformation 1  $\rightarrow$  decaying frame

$$\frac{d\rho_K}{dt} = -i \left( H_K \rho_K - \rho_K H_K^\dagger \right) + \sum_i \mathcal{J}_{L_i, K} \rho_K.$$

- Observation: in many practical cases

$$[K, L_i] = -\gamma_{i, K} L_i / 2 \quad \text{for some constant } \gamma_{i, K}$$

then

$$L_{i, K} \equiv e^{Kt} L_i e^{-Kt} = L_i + [K, L_i]t + \frac{1}{2!} [K, [K, L_i]]t^2 + \dots = e^{-\gamma_{i, K} t / 2} L_i.$$

- Pseudo*-time-evolution operator

$$U \equiv \mathbf{T} e^{-i \int_0^t H_K(t') dt'}$$

Also note that

$$U^{-1} = \tilde{\mathbf{T}} e^{+i \int_0^t H_K dt'}, \quad U^\dagger = \tilde{\mathbf{T}} e^{+i \int_0^t H_K^\dagger dt'}, \quad (U^{-1})^\dagger = \mathbf{T} e^{-i \int_0^t H_K^\dagger dt'}.$$



# Time Average Formalism for an Open System (Cont'd)

- Let  $\rho_U \equiv U^{-1} \rho_K (U^{-1})^\dagger$  then

$$\frac{d\rho_U}{dt} = U^{-1} \dot{\rho}_K (U^{-1})^\dagger + U^{-1} i (H_K \rho_K - \rho_K H_K) (U^{-1})^\dagger,$$

- Transformation 2  $\rightarrow$  pseudo-rotating frame

$$\begin{aligned} \frac{d\rho_U}{dt} &= \sum_i U^{-1} \mathcal{F}_{L_{i,K}} \rho_K (U^{-1})^\dagger = \sum_i L_{i,U} \rho_U L_{i,U}^\dagger \\ &= \sum_i \mathcal{F}_{L_{i,U}} \rho_U = \mathcal{F}_{\text{tot}} \rho_U \quad (L_{i,U} \equiv U^{-1} L_{i,K} U, \mathcal{F}_{\text{tot}} \equiv \sum_i \mathcal{F}_{L_{i,U}}) \end{aligned}$$

$$\begin{aligned} \rho_U(t) &= e^{\int_0^t \mathcal{F}_{\text{tot}} dt} \rho_0 \\ &= \rho_0 + \sum_i \int_0^t dt_1 L_{i,U}(t_1) \rho_0 L_{i,U}^\dagger(t_1) + \frac{1}{2!} \sum_{i,j} \int_0^t dt_1 \int_0^{t_1} dt_2 \\ &\quad \times L_{i,U}(t_1) L_{j,U}(t_2) \rho_0 L_{j,U}^\dagger(t_2) L_{i,U}^\dagger(t_1) + \dots \end{aligned}$$

# Time Average Formalism for an Open System (Cont'd)

- Up to 1st order of decay constants

$$\rho_U(t) \approx \left(1 + \int_0^t \mathcal{F}_{\text{tot}} dt\right) \rho_0 \equiv (1 + \mathcal{F}_{\text{int}}) \rho_0$$

- Return to  $\rho_K$  and take time average

$$\bar{\rho}_K(t) = \overline{U(1 + \mathcal{F}_{\text{int}})\rho_0 U^\dagger} \equiv \mathcal{E}[\rho_0] = \sum_k \mathcal{E}_k[\rho_0]$$

- Expansion of  $L_{i,U}$  and  $\mathcal{F}_{\text{int}}$  according to the order of  $H_K$

$$\begin{aligned} L_{i,U} &= U^{-1} L_{i,K} U \\ &= e^{-\gamma_{i,K} t/2} \{L_i + [L_i, U_1] + ([L_i, U_2] - U_1[L_i, U_1]) + \dots\} \\ &\equiv L_{i,0} + L_{i,1} + L_{i,2} + \dots \\ \mathcal{F}_{\text{int}} &= \int_0^t \mathcal{F}_{\text{tot}} dt \equiv \int_0^t \mathcal{F}_0^U dt + \int_0^t \mathcal{F}_1^U dt + \int_0^t \mathcal{F}_2^U dt + \dots \\ &\equiv \mathcal{F}_0 + \mathcal{F}_1 + \mathcal{F}_2 + \dots \end{aligned}$$

# Time Average Formalism for an Open System (Cont'd)

$$\mathcal{F}_0^U \rho \equiv \sum_i L_{i,0} \rho L_{i,0}^\dagger = \sum_i e^{-\gamma_{i,K} t} L_i \rho L_i$$

$$\mathcal{F}_1^U \rho \equiv \sum_i \left( L_{i,0} \rho L_{i,1}^\dagger + L_{i,1} \rho L_{i,0}^\dagger \right)$$

$$\mathcal{F}_2^U \rho \equiv \sum_i \left( L_{i,0} \rho L_{i,2}^\dagger + L_{i,1} \rho L_{i,1}^\dagger + L_{i,2} \rho L_{i,0}^\dagger \right).$$

$$\mathcal{E}_0[\rho] = (1 + \overline{\mathcal{F}_0})\rho = (1 + \mathcal{F}_0)\rho,$$

$$\mathcal{E}_1[\rho] = \overline{\mathcal{F}_1}\rho + \overline{U_1}(1 + \mathcal{F}_0)\rho + \overline{[(1 + \mathcal{F}_0)\rho]U_1^\dagger},$$

$$\begin{aligned} \mathcal{E}_2[\rho] = & \overline{\mathcal{F}_2}\rho + \overline{U_2}(1 + \mathcal{F}_0)\rho + \overline{U_1[(1 + \mathcal{F}_0)\rho]U_1^\dagger} \\ & + \overline{[(1 + \mathcal{F}_0)\rho]U_2^\dagger} + \overline{(\mathcal{F}_1\rho)U_1^\dagger} + \overline{U_1(\mathcal{F}_1\rho)}, \end{aligned}$$

$$\mathcal{F}_0[\rho] = (1 - \mathcal{F}_0)\rho,$$

...

# Time Average Formalism for an Open System (Cont'd)

- Time-averaged master equation for  $\bar{\rho}_K$

$$i \dot{\bar{\rho}}_K(t) = i \dot{\mathcal{E}}[\rho_0] = i \dot{\mathcal{E}}[\mathcal{F}[\bar{\rho}_K(t)]] = i \sum_{k=0}^{\infty} \sum_{j=0}^k \dot{\mathcal{E}}_j[\mathcal{F}_{k-j}[\bar{\rho}_K(t)]]$$

$$\equiv \sum_{k=0}^{\infty} \mathcal{L}_k[\bar{\rho}_K(t)],$$

$$\mathcal{L}_0[\rho] = i \mathcal{J}_0^U \rho \quad (\neq 0),$$

$$\mathcal{L}_1[\rho] = \overline{H_K} \rho - \rho \overline{H_K}^\dagger,$$

$$\mathcal{L}_2[\rho] = \overline{H_K U_1} \rho + \overline{H_K \rho U_1}^\dagger - \overline{U_1 \rho H_K}^\dagger - \rho \overline{U_1 H_K}^\dagger \\ + \overline{H_K (\mathcal{J}_1 \rho)} - (\mathcal{J}_1 \rho) \overline{H_K}^\dagger$$

...

# Time Average Formalism for an Open System (Cont'd)

- Time-averaged master equation for  $\rho$

$$\begin{aligned}
 i\dot{\bar{\rho}}(t) &= -i \sum_i \mathcal{K}_{L_i} \bar{\rho} + e^{-Kt} \left( \mathcal{L}_0[\bar{\rho}_K] + \mathcal{L}_1[\bar{\rho}_K] + \mathcal{L}_2[\bar{\rho}_K] \right) e^{-Kt} \\
 &= i \sum_i (\mathcal{J}_{L_i} \rho - \mathcal{K}_{L_i} \rho) + [\bar{H}, \bar{\rho}] + \overline{H\tilde{U}_1} \bar{\rho} + \overline{H\bar{\rho}\tilde{U}_1^\dagger} \\
 &\quad - \overline{\tilde{U}_1 \bar{\rho} H} - \overline{\bar{\rho} \tilde{U}_1^\dagger H} + \overline{H(\tilde{\mathcal{J}}_1 \bar{\rho})} - \overline{(\tilde{\mathcal{J}}_1 \bar{\rho}) H} \\
 &= [H_{\text{eff}}, \bar{\rho}] + i \sum_i (\mathcal{J}_{L_i} \rho - \mathcal{K}_{L_i} \rho) + \left\{ \frac{1}{2} (A - A^\dagger), \rho \right\} \\
 &\quad + \overline{H\bar{\rho}\tilde{U}_1^\dagger} - \overline{\tilde{U}_1 \bar{\rho} H} + \overline{H(\tilde{\mathcal{J}}_1 \bar{\rho})} - \overline{(\tilde{\mathcal{J}}_1 \bar{\rho}) H}^\dagger
 \end{aligned}$$

where  $H_{\text{eff}}$  is the same as before with  $A \equiv \overline{H\tilde{U}_1}$ ,  $A^\dagger \equiv \overline{\tilde{U}_1^\dagger H}$ ,  $\tilde{U}_1 \equiv e^{-Kt} U_1 e^{Kt}$ , and  $\tilde{\mathcal{J}}_1 \bar{\rho} \equiv e^{-Kt} (\mathcal{J}_1 \bar{\rho}_K) e^{-Kt}$ .

# Time Average Formalism for an Open System (Cont'd)

- Another assumption for time average process

$$\overline{O_K} = \overline{e^{Kt} O e^{-Kt}} \approx e^{Kt} \overline{O} e^{-Kt} \quad \text{for a generic operator } O$$

(A decay process is relatively slower than any other oscillatory process.)

- Master equation up to 2nd order of Hamiltonian (and up to 1st order of decay constants)

$$i \dot{\bar{\rho}} = [H_{\text{eff}}, \bar{\rho}] + \sum_n \mathcal{D}_{L_n, L_n^\dagger} \bar{\rho} + \sum_{m,n} \frac{2}{\tilde{\omega}_{mn}^-} \left[ \mathcal{D}_{l_m, l_n^\dagger} \bar{\rho} - \mathcal{D}_{l_m^\dagger, l_n} \bar{\rho} \right] \\ + \overline{H(\tilde{\mathcal{J}}_1 \bar{\rho})} - (\overline{\tilde{\mathcal{J}}_1 \bar{\rho}}) H,$$

with  $e^{Kt} h_n e^{-Kt} = h_n e^{-\frac{\delta_n}{2} t}$ ,  $\tilde{\omega}_n \equiv \omega_n + i \frac{\delta_n}{2}$ ,  $\frac{1}{\tilde{\omega}_{mn}^\pm} \equiv \frac{1}{2} \left( \frac{1}{\tilde{\omega}_m} \pm \frac{1}{\tilde{\omega}_n^*} \right)$ ,  
and

$$H_{\text{eff}} \equiv H_0 + \sum_{m,n} \frac{1}{\tilde{\omega}_{mn}^+} [l_m, l_n^\dagger].$$

## EXAMPLES

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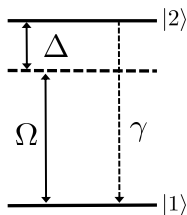
## Example: 2-level system

- Hamiltonian & decay operator

$$H = he^{i\Delta t} + h^\dagger e^{-i\Delta t},$$
$$h = \frac{\Omega}{2} |1\rangle\langle 2|, L = \sqrt{\gamma} |1\rangle\langle 2|$$

- Relation between decay operators

$$[\frac{1}{2}L^\dagger L, L] = \frac{\gamma}{2}L$$
$$\implies H_K = he^{i\tilde{\Delta}t} + h^\dagger e^{-i\tilde{\Delta}t}, \quad \tilde{\Delta} \equiv \Delta + i\gamma/2$$
$$U_1 = \frac{1}{\tilde{\Delta}} \left( -he^{i\tilde{\Delta}t} + h^\dagger e^{-i\tilde{\Delta}t} \right) - \frac{1}{\tilde{\Delta}} \left( -h + h^\dagger \right),$$
$$\tilde{U}_1 = \frac{1}{\Delta} \left( -he^{i\Delta t} + h^\dagger e^{-i\Delta t} \right) - \frac{1}{\tilde{\Delta}} \left( -he^{\gamma t/2} + h^\dagger e^{-\gamma t/2} \right).$$





# Example: 2-level system (Cont'd)

- Effective master equation (ME)

$$i\dot{\bar{\rho}} = [H_{\text{eff}}, \bar{\rho}] + \mathcal{D}_{L, L^+}\bar{\rho} + \overline{H(\tilde{\mathcal{J}}_1\bar{\rho})} - (\overline{\tilde{\mathcal{J}}_1\bar{\rho}})H$$

$$H_{\text{eff}} = -\frac{\Omega^2\Delta}{4\Delta^2 + \gamma^2}\sigma_z \xrightarrow{\gamma=0} -\frac{\Omega^2}{4\Delta}\sigma_z \text{ (ac-Stark shift)}$$

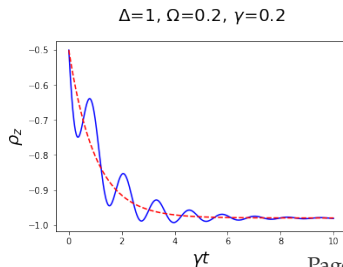
$$\overline{H(\tilde{\mathcal{J}}_1\bar{\rho})} = \left[ (\overline{\tilde{\mathcal{J}}_1\bar{\rho}})H \right]^\dagger = \frac{i\Omega^2\gamma}{4\Delta^2 + \gamma^2} (|2\rangle\langle 2| \bar{\rho}\sigma_z - |1\rangle\langle 2| \bar{\rho} |2\rangle\langle 1|)$$

with  $\sigma_z \equiv |2\rangle\langle 2| - |1\rangle\langle 1|$ .

- Plot of atomic polarization

$$\rho_z \equiv \langle \sigma_z \rangle$$

(blue solid: original ME,  
red dashed: effective ME)

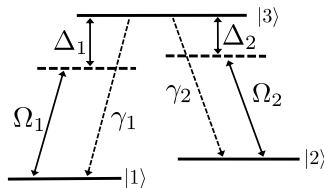


# Example: 3-level (Raman) system

- Hamiltonian & decay operator

$$H = h_1 e^{i\Delta_1 t} + h_2 e^{i\Delta_2 t} + \text{h.c.},$$

$$h_i = \frac{\Omega_i}{2} |i\rangle\langle 3|, \quad L_i = \sqrt{\gamma_i} |i\rangle\langle 3|$$



- Relation between decay operators

$$[(L_1^\dagger L_1 + L_2^\dagger L_2)/2, L_i] = (\gamma/2)L_i \quad (\gamma \equiv \gamma_1 + \gamma_2)$$

- Effective Hamiltonian

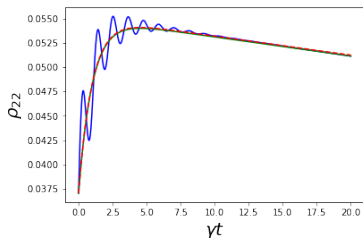
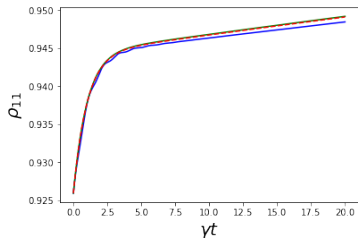
$$H_{\text{eff}} = \sum_i \frac{\Omega_i^2 \Delta_i}{4\Delta_i^2 + \gamma^2} (|i\rangle\langle i| - |3\rangle\langle 3|) + \left[ \frac{(\Delta_1 + \Delta_2)\Omega_1\Omega_2}{8(\Delta_1 - i\gamma/2)(\Delta_2 + i\gamma/2)} |1\rangle\langle 2| e^{i\Delta_{12}t} + \text{h.c.} \right].$$

⇒ Agrees with a different approach (e.g., Reiter & Sørensen) Page 25

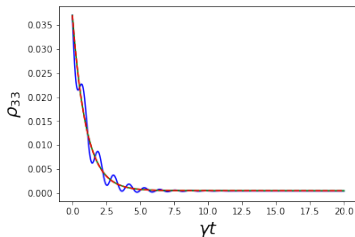
# Example: 3-level (Raman) system (Cont'd)

○ Expectation values of populations:  $\rho_{ii} = \langle i | \rho | i \rangle$

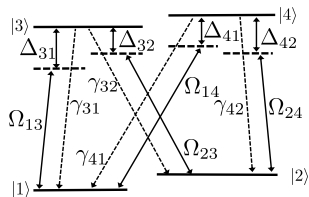
$\Delta_1=1.0, \Delta_2=1.1, \Omega_1=0.0, \Omega_2=0.2, \gamma_1=0.1, \gamma_2=0.1$      $\Delta_1=1.0, \Delta_2=1.1, \Omega_1=0.0, \Omega_2=0.2, \gamma_1=0.1, \gamma_2=0.1$



$\Delta_1=1.0, \Delta_2=1.1, \Omega_1=0.0, \Omega_2=0.2, \gamma_1=0.1, \gamma_2=0.1$

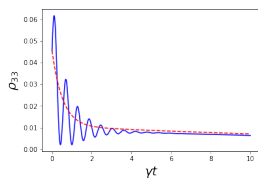
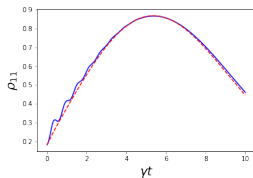


# Example: 4-level double- $\Lambda$ system



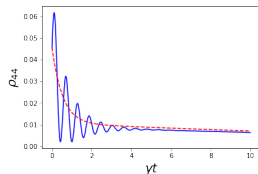
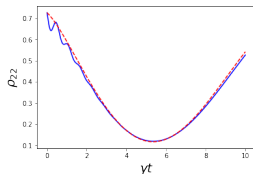
$\Delta_{31}=1.0, \Delta_{32}=1.0, \Delta_{41}=1.0, \Delta_{42}=1.0, \Omega=0.2, \gamma=0.1$

$\Delta_{31}=1.0, \Delta_{32}=1.0, \Delta_{41}=1.0, \Delta_{42}=1.0, \Omega=0.2, \gamma=0.1$



$\Delta_{31}=1.0, \Delta_{32}=1.0, \Delta_{41}=1.0, \Delta_{42}=1.0, \Omega=0.2, \gamma=0.1$

$\Delta_{31}=1.0, \Delta_{32}=1.0, \Delta_{41}=1.0, \Delta_{42}=1.0, \Omega=0.2, \gamma=0.1$



## SUMMARY AND OUTLOOK

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# Summary and Outlook

- Advantages over adiabatic elimination
  - easy and simple to use
  - need no knowledge of levels to be removed
  - provide infinite hierarchy in principle
  - An initial state can have excited state populations.
- Still lengthy and tedious algebra for *higher order* calculation  
→ Numerous terms appear in 4th order perturbation.
- Other approaches to be considered
  - Nonequilibrium functional integral (insensitive to operator ordering) + RG (successive flow approximation)
  - Extending flow equation approach to an open system
  - Machine learning for numerical quantization